

PIAB SERIES

LINEAR SERVO MOTOR ACTUATOR
IRON CORE

PBA
SYSTEMS

www.pbasystems.com.sg

PART NUMBERING SYSTEM

■ Coil Assembly

PIAB - P1 - S - TM - 1.0 - FC - HC - E1.0 - O - 1060 - 00

MOTOR MODEL	
P1	PIX200-027-030
P2	PIX200-027-050
P3	PIX200-040-050

CONNECTION TYPE	
S	Series
P	Parallel

THERMAL PROTECTION	
TC*	PT 100 Sensor
TM**	Thermostat

CABLE LENGTH***	
0.5	0.5m
1.0	1.0m
2.0	2.0m
3.0	3.0m
4.0	4.0m
5.0	5.0m

POWER CABLE OPTIONS	
NF	No Ferrite Core (Flying Leads)
FC	Ferrite Core (Recommended)
9NF	No Ferrite Core, D Sub 9 pins Female Connector
CNF	No Ferrite Core, Circular Quick Lock 6 pins Male Connector

DESIGN VERSIONS	
00	Standard
01	Customized Version
:	

EFFECTIVE STROKE (mm)	
100-1700	Open Type
100-1700	Covered Type
100-1060	Bellow Type

COVER	
O	Open
C	Covered
B	Bellow

ENCODER RESOLUTION	
EA	Analog
E0.5	0.5um
E1.0	1.0um

HALL SENSOR AND CONNECTOR OPTIONS	
NH	No Hall Sensor
H	Hall Sensor with Flying Leads (No Connector)
HC	Hall Sensor with 9 pins D Sub Male Connector
CHC	Hall Sensor with 5 pins Circular Quick Lock Male Connector

* TC - Sensor output to temperature controller
 ** TM - On/Off switch, triggers at 100°C
 *** Encoder, power & hall cable

LINEAR ACTUATOR

DX B / BT

PIX / PIXA

PSM / PSME

CVC

CVCA

RVCA

PDDR / PCA

PLA

PDAB

PIAB

OCTO

PRG

LINEAR ENCODER

MAXTUNE

DELTA

MITSUBISHI

TECHNOSOFT

PIAB-P1

- Iron Core Actuator
- Peak force to 542N, Continuous force to 108N

PIAB SERIES

Iron Core Actuator

LINEAR ACTUATOR

DX B / BT

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LINEAR ENCODER

MAXTUNE

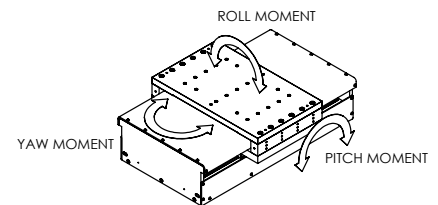
DELTA

TECHNOSOFT

SPECIFICATION		MODEL	
		PIAB-P1	
Motor Parameters	Unit	S	P
Peak Force	N	542	
Continuous Force @ 105°C*	N	108	
Continuous Stall Force @ 105°C*	N	77	
Peak Power @ 105°C	W	1823	
Continuous Power @ 105°C*	W	73	
Peak Current	A ^{pk}	30.4	60.8
Continuous Current @ 105°C*	A ^{pk}	6.1	12.2
Continuous Stall Current @ 105°C*	Arms	4.3	8.6
Force Constant	N/A ^{pk}	17.8	8.9
Back EMF Constant	V ^{pk} /m/s	20.5	10.3
Coil Resistance L-L @ 25°C	Ohm	1.9	0.5
Coil Resistance L-L @ 120°C*	Ohm	2.6	0.7
Inductance L-L @ 1kHz	mH	4.9	1.2
Motor Constant @ 25°C*	N/√W	14.9	
Motor Constant @ 120°C*	N/√W	12.7	
Max Terminal Voltage	Vdc	600	
Accuracy			
Repeatability **	um	± 2um	
Accuracy ***	um	± 20um / 300mm	
Straightness ***	um	± 8um / 300mm	
Flatness ***	um	± 8um / 300mm	
Linear Guide Rated Load and Static Moment			
Model Code		LM Guide	
Block Quantity		4	
Maximum bearing load	N	3125	
Pitch moment	Nm	287	
Yaw moment	Nm	287	
Roll moment	Nm	218	

Notes:

1. A^{pk} = 1.414 * Arms; V^{pk} = 1.414 * Vrms.
2. Specifications tolerance – inductance +/-15%, all others +/-10%.
3. * Ambient temperature 25°C, heat dissipation by natural convection, without heat sink attached.
4. ** Depend on encoder resolution.
5. Peak force and current - 1 second duration.
6. *** Specific accuracy, straightness and flatness requirement, contact PBA for more information.
7. For customized stroke length, contact PBA.
8. For different motor models, contact PBA.



PIAB-P2

- Iron Core Actuator
- Peak force to 893N, Continuous force to 179N

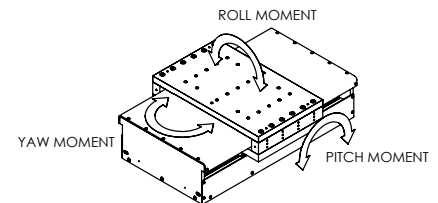
PIAB SERIES

Iron Core Actuator

SPECIFICATION		MODEL	
		PIAB-P2	
Motor Parameters	Unit	S	P
Peak Force	N	893	
Continuous Force @ 105°C*	N	179	
Continuous Stall Force @ 105°C*	N	126	
Peak Power @ 105°C	W	2323	
Continuous Power @ 105°C*	W	93	
Peak Current	A ^{pk}	29.3	88.7
Continuous Current @ 105°C*	A ^{pk}	5.9	11.7
Continuous Stall Current @ 105°C*	Arms	4.15	8.30
Force Constant	N/A ^{pk}	30.4	15.2
Back EMF Constant	V ^{pk} /m/s	35	17.5
Coil Resistance L-L @ 25°C	Ohm	2.6	0.7
Coil Resistance L-L @ 120°C*	Ohm	3.6	0.9
Inductance L-L @ 1kHz	mH	7.1	1.8
Motor Constant @ 25°C*	N/√W	21.8	
Motor Constant @ 120°C*	N/√W	18.5	
Max Terminal Voltage	Vdc	600	
Accuracy			
Repeatability **	mm	± 2um	
Accuracy ***	mm	± 20um / 300mm	
Straightness ***	um	± 8um / 300mm	
Flatness ***	um	± 8um / 300mm	
Linear Guide Rated Load and Static Moment			
Model Code		LM Guide	
Block Quantity		4	
Maximum bearing load	N	3125	
Pitch moment	Nm	287	
Yaw moment	Nm	287	
Roll moment	Nm	218	

Notes:

1. $A^{pk} = 1.414 \cdot \text{Arms}$; $V^{pk} = 1.414 \cdot V_{rms}$.
2. Specifications tolerance – inductance +/-15%, all others +/-10%.
3. * Ambient temperature 25°C, heat dissipation by natural convection, without heat sink attached.
4. ** Depend on encoder resolution.
5. Peak force and current - 1 second duration.
6. *** Specific accuracy, straightness and flatness requirement, contact PBA for more information.
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PIAB-P3

- Iron Core Actuator
- Peak force to 943N, Continuous force to 189N

PIAB SERIES

Iron Core Actuator

LINEAR ACTUATOR

DX B / BT

PIX / PIXA

PSM / PSME

CVC

CVCA

RVCA

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PLA

PBAB

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PRG

LINEAR ENCODER

MAXTUNE

DELTA

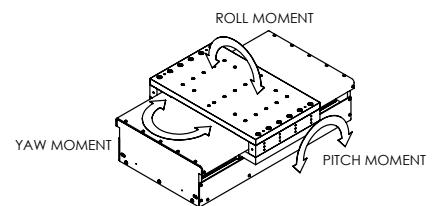
MITSUBISHI

TECHNOSOFT

SPECIFICATION		MODEL	
		PIAB-P3	
Motor Parameters	Unit	S	P
Peak Force	N	1515	
Continuous Force @ 105°C*	N	303	
Continuous Stall Force @ 105°C*	N	214	
Peak Power @ 105°C	W	2662	
Continuous Power @ 105°C*	W	106	
Peak Current	A ^{pk}	20.5	41.0
Continuous Current @ 105°C*	A ^{pk}	4.1	8.2
Continuous Stall Current @ 105°C*	Arms	2.9	5.8
Force Constant	N/A ^{pk}	73.9	37.0
Back EMF Constant	V ^{pk} /m/s	85.0	42.5
Coil Resistance L-L @ 25°C	Ohm	6.1	1.5
Coil Resistance L-L @ 105°C*	Ohm	8.4	2.1
Inductance L-L @ 1kHz	mH	60.6	15.1
Motor Constant @ 25°C*	N/√W	34.6	
Motor Constant @ 120°C*	N/√W	29.4	
Max Terminal Voltage	Vdc	600	
Accuracy			
Repeatability **	mm	± 2um	
Accuracy ***	mm	± 20um / 300mm	
Straightness ***	um	± 8um / 300mm	
Flatness ***	um	± 8um / 300mm	
Linear Guide Rated Load and Static Moment			
Model Code		LM Guide	
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Maximum bearing load	N	3125	
Pitch moment	Nm	287	
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Notes:

1. $A^{pk} = 1.414 * Arms$; $V^{pk} = 1.414 * Vrms$.
2. Specifications tolerance – inductance +/-15%, all others +/-10%.
3. * Ambient temperature 25°C, heat dissipation by natural convection, without heat sink attached.
4. ** Depend on encoder resolution.
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7. For customized stroke length, contact PBA.
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PIAB - OPEN TYPE

LINEAR ACTUATOR

DX / B / BT

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PSM / PSME

CVC

CVCA

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PLA

PDAB

PIAB

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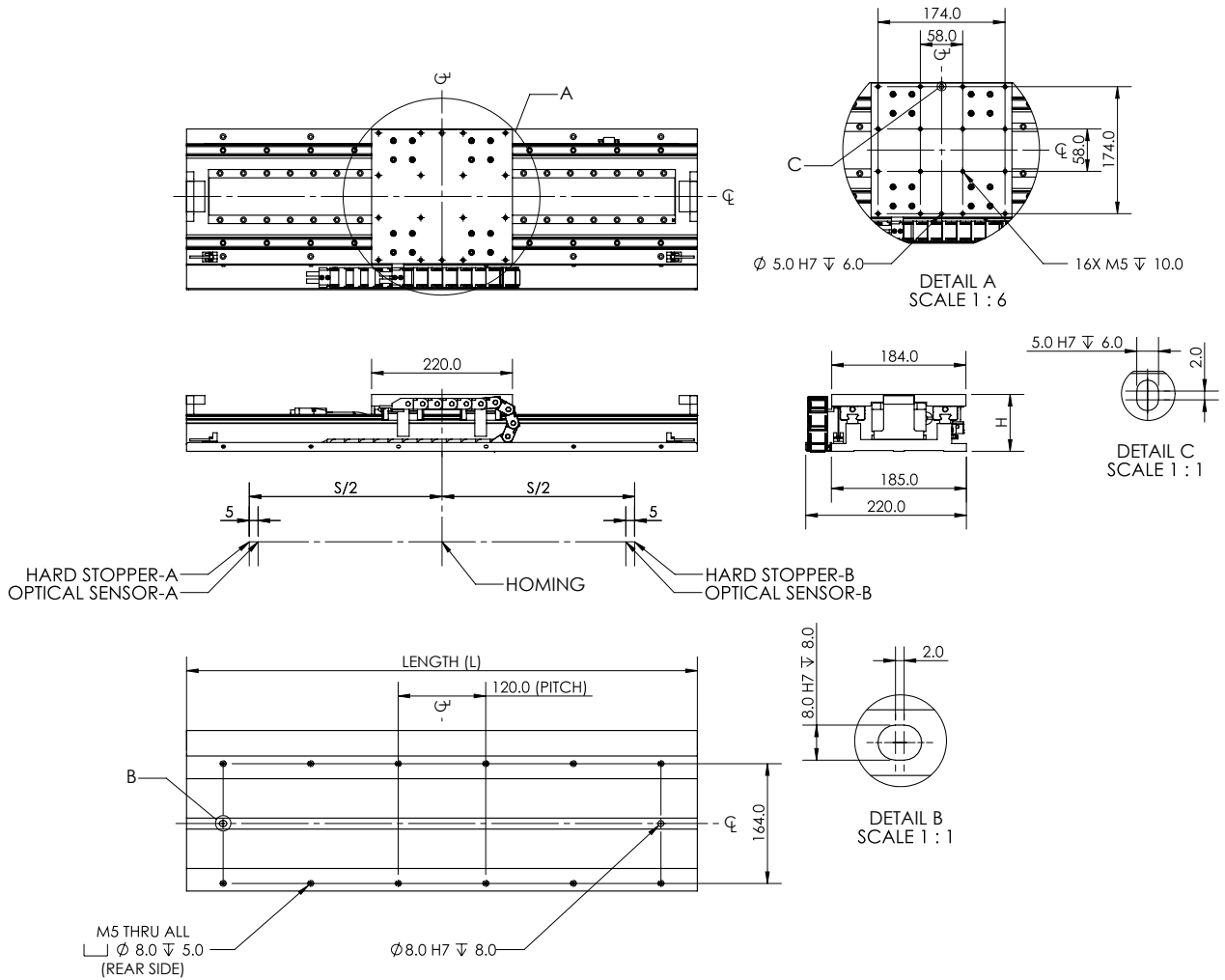
LINEAR ENCODER

MAXTUNE

DELTA

MITSUBISHI

TECHNOSOFT

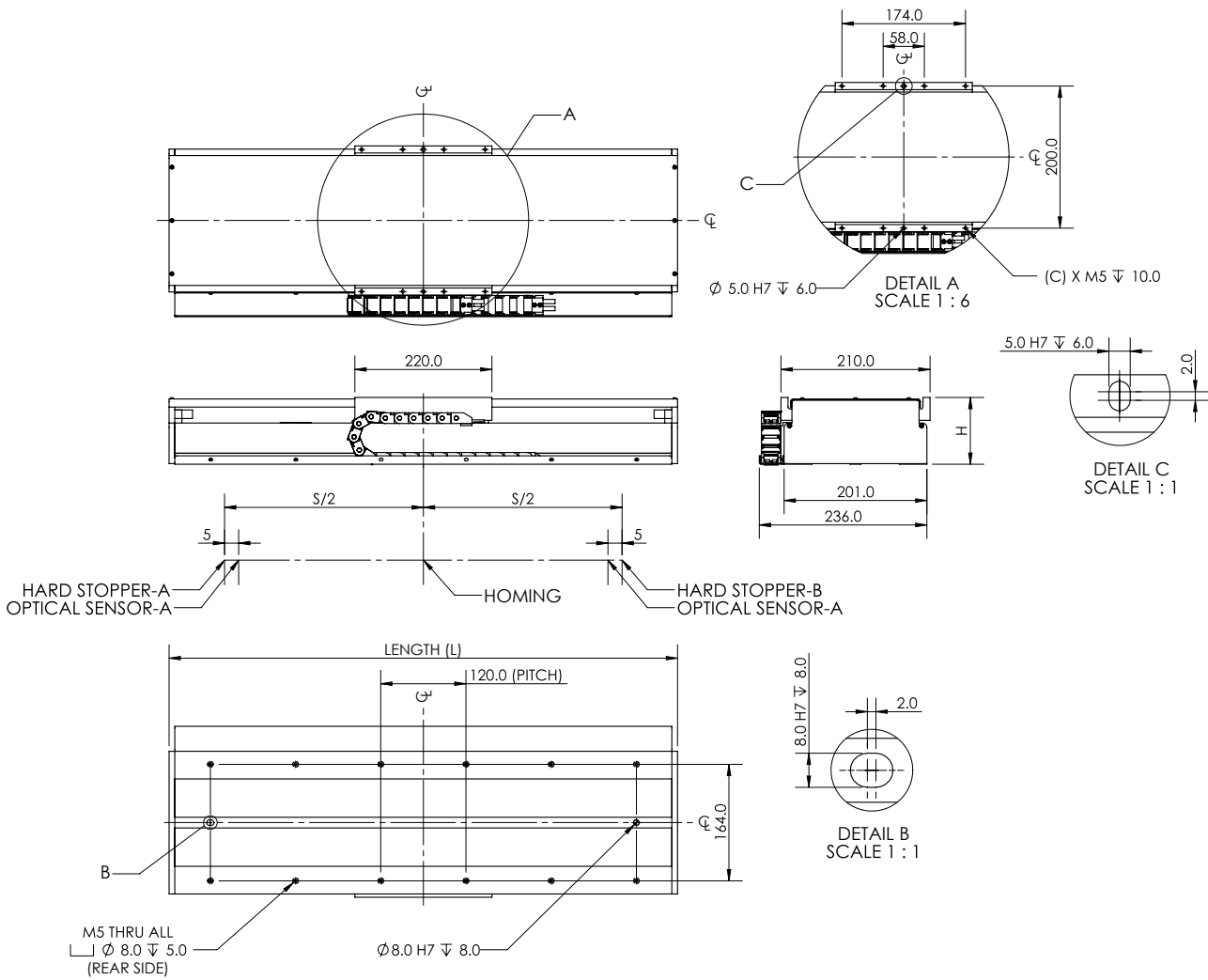


MOTOR MODEL	HEIGHT (H) mm	STROKE (S) mm	ACTUATOR (L) mm	STROKE/ACTUATOR LENGTH (S) / (L) mm	SLIDER MASS kg	MODULE MASS (W) kg
PIX200-027-030	65	MIN:100 MAX:1700	MIN:380 MAX:1980	S=100+(Multiple of 64mm) L=S+220+(60mm)	3.1	MIN : 8.6 MAX: 40.5 W=8.6 + (Multiple of 1.2kg)
PIX200-027-050					3.8	MIN : 9.8 MAX: 41.8 W=9.8 + (Multiple of 1.2kg)
PIX200-040-050	78				4.9	MIN : 11.0 MAX: 42.9 W=11.0 + (Multiple of 1.2kg)

Notes:

1. Slider Mass = Coil Mass + Carriage Mass
2. Module mass increment of 1.2kg per 64mm

PIAB - COVERED TYPE



MOTOR MODEL	HEIGHT (H) mm	STROKE (S) mm	ACTUATOR (L) mm	STROKE/ACTUATOR LENGTH (S) / (L) mm	SLIDER MASS kg	MODULE MASS (W) kg
PIX200-027-030	80	MIN:100 MAX:1700	MIN:396 MAX:1996	S=100+(Multiple of 64mm) L=S+220+(76mm)	3.5	MIN : 11.2 MAX: 46.2 W=11.2 + (Multiple of 1.4kg)
PIX200-027-050					4.2	MIN : 12.5 MAX: 47.5 W=12.5 + (Multiple of 1.4kg)
PIX200-040-050	95				5.3	MIN : 13.6 MAX: 48.6 W=13.6 + (Multiple of 1.4kg)

Notes:

- Slider Mass = Coil Mass + Carriage Mass
- Module mass increment of 1.4kg per 64mm

LINEAR ACTUATOR

DX B / BT

PIX / PIXA

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LINEAR ENCODER

MAXTUNE

DELTA

MITSUBISHI

TECHNOSOFT

PIAB - BELLOWS TYPE

LINEAR ACTUATOR

DX / B / BT

PIX / PIXA

PSM / PSME

CVC

CVCA

RVCA

PDDR

PCA

PLA

PDAB

PIAB

OCTO

PRG

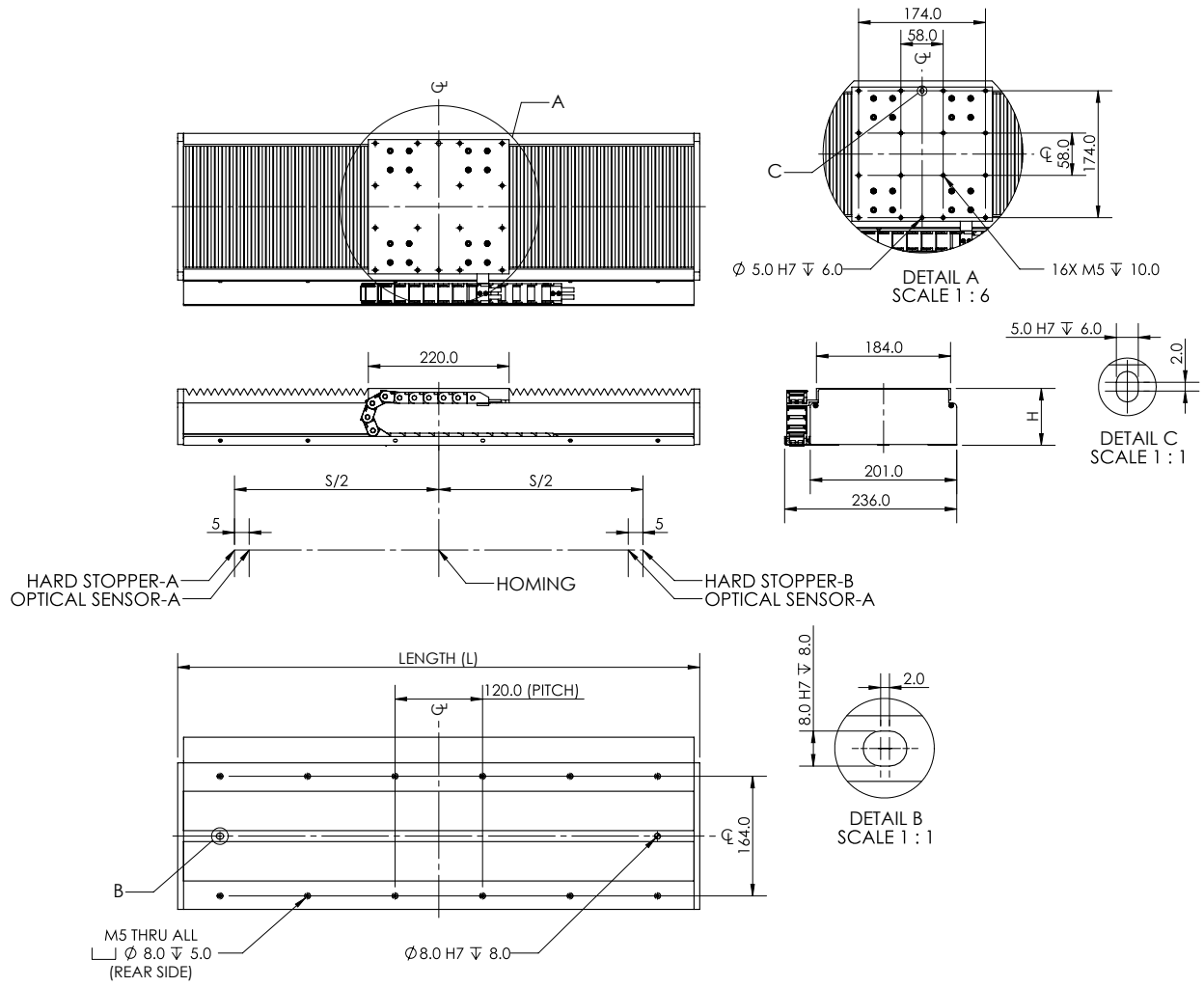
LINEAR ENCODER

MAXTUNE

DELTA

MITSUBISHI

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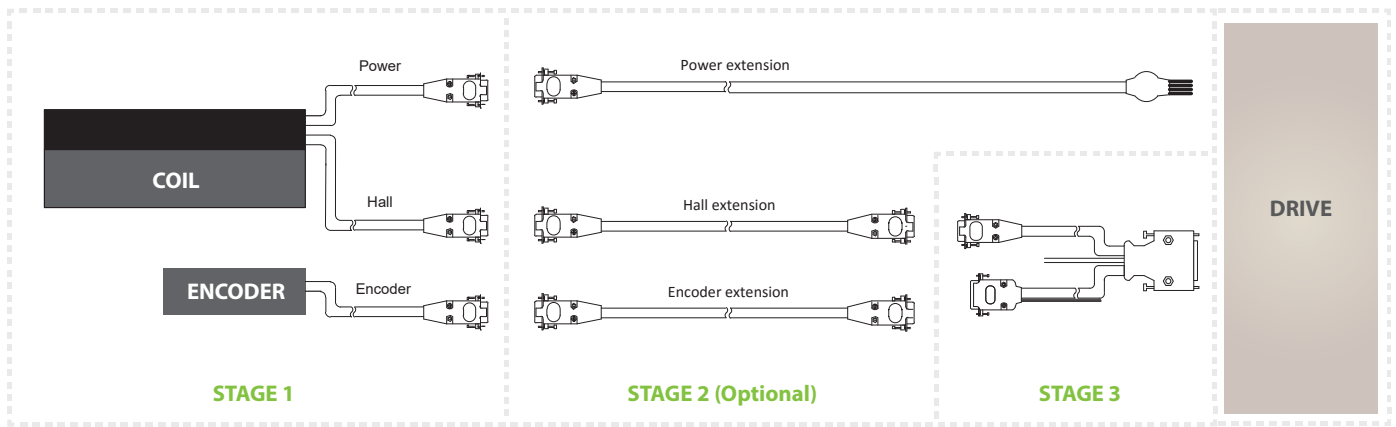


MOTOR MODEL	HEIGHT (H) mm	STROKE (S) mm	ACTUATOR (L) mm	STROKE/ACTUATOR LENGTH (S) / (L) mm	SLIDER MASS kg	MODULE MASS (W) kg	
PIX200-027-030	65	MIN:100 MAX:1060	MIN:428 MAX:1868	S=100+(Multiple of 64mm) L=S+220+(200mm)	3.3	MIN : 10.5 MAX: 30.0	W=10.5 + (Multiple of 1.3kg)
PIX200-027-050					4.0	MIN : 11.7 MAX: 31.2	W=11.7 + (Multiple of 1.3kg)
PIX200-040-050	78	5.1	MIN : 12.9 MAX: 32.4		W=12.9 + (Multiple of 1.3kg)		

Notes:

- Slider Mass = Coil Mass + Carriage Mass
- Module mass increment of 1.3kg per 64mm

CABLE OPTION



STAGE 1

POWER AND HALL CABLE OPTION

PIAB-P1-S-TM-1.0-FC-HC-E1.0-O-1060-00

POWER CABLE OPTIONS

NF		<table border="1"> <tr><td>M1</td><td>Grey</td></tr> <tr><td>M2</td><td>Brown</td></tr> <tr><td>M3</td><td>Black</td></tr> <tr><td>PE</td><td>Yellow</td></tr> <tr><td>Temp sensor 1</td><td>Orange / Black</td></tr> <tr><td>Temp sensor 2</td><td>Orange</td></tr> </table>	M1	Grey	M2	Brown	M3	Black	PE	Yellow	Temp sensor 1	Orange / Black	Temp sensor 2	Orange															
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	P1	M1	Grey																										
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	9 Pin D-sub Female																												
CNF		<table border="1"> <tr><td>P1</td><td>M1</td><td>Grey</td></tr> <tr><td>P2</td><td>M2</td><td>Black</td></tr> <tr><td>P3</td><td>M3</td><td>Brown</td></tr> <tr><td>P4</td><td>Temp sensor 1</td><td>Red</td></tr> <tr><td>P5</td><td>Temp sensor 2</td><td>Black</td></tr> <tr><td>P6</td><td>PE</td><td>Yellow & Green</td></tr> </table>	P1	M1	Grey	P2	M2	Black	P3	M3	Brown	P4	Temp sensor 1	Red	P5	Temp sensor 2	Black	P6	PE	Yellow & Green									
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P6	PE	Yellow & Green																											
	Push Pull 6 Pin Male																												

HALL SENSOR OPTIONS

H		<table border="1"> <tr><td>Hall A</td><td>White</td></tr> <tr><td>Hall B</td><td>Green</td></tr> <tr><td>Hall C</td><td>Blue</td></tr> <tr><td>5V</td><td>Red</td></tr> <tr><td>0V</td><td>Black</td></tr> </table>	Hall A	White	Hall B	Green	Hall C	Blue	5V	Red	0V	Black					
	Hall A	White															
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Hall C	Blue																
5V	Red																
0V	Black																
HC		<table border="1"> <tr><td>P1</td><td>Hall A</td><td>White</td></tr> <tr><td>P2</td><td>Hall B</td><td>Green</td></tr> <tr><td>P3</td><td>Hall C</td><td>Blue</td></tr> <tr><td>P4</td><td>5V</td><td>Red</td></tr> <tr><td>P5</td><td>0V</td><td>Black</td></tr> </table>	P1	Hall A	White	P2	Hall B	Green	P3	Hall C	Blue	P4	5V	Red	P5	0V	Black
	P1	Hall A	White														
P2	Hall B	Green															
P3	Hall C	Blue															
P4	5V	Red															
P5	0V	Black															
	9 Pin D-sub Male																
CHC		<table border="1"> <tr><td>P1</td><td>Hall A</td><td>White</td></tr> <tr><td>P2</td><td>Hall B</td><td>Green</td></tr> <tr><td>P3</td><td>Hall C</td><td>Blue</td></tr> <tr><td>P4</td><td>5V</td><td>Red</td></tr> <tr><td>P5</td><td>0V</td><td>Black</td></tr> </table>	P1	Hall A	White	P2	Hall B	Green	P3	Hall C	Blue	P4	5V	Red	P5	0V	Black
	P1	Hall A	White														
P2	Hall B	Green															
P3	Hall C	Blue															
P4	5V	Red															
P5	0V	Black															
	Push Pull 5 Pin Male																

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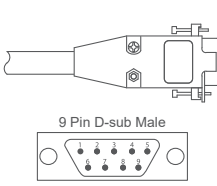
DELTA

MITSUBISHI

TECHNOSOFT

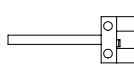
PIAB CABLE PIN OUT

ENCODER CONNECTOR - 9 PIN D-SUB MALE



	RH200X / RH200Z	RH200B
P1	0V DC	0V DC
P2	A+	Sine+
P3	Z+	Z+
P4	B+	Cosine+
P5	+5V DC	+5V DC
P6	A-	Sine-
P7	Z-	Z-
P8	B-	Cosine-
P9	Inner	Inner
Casing	Outer	Outer

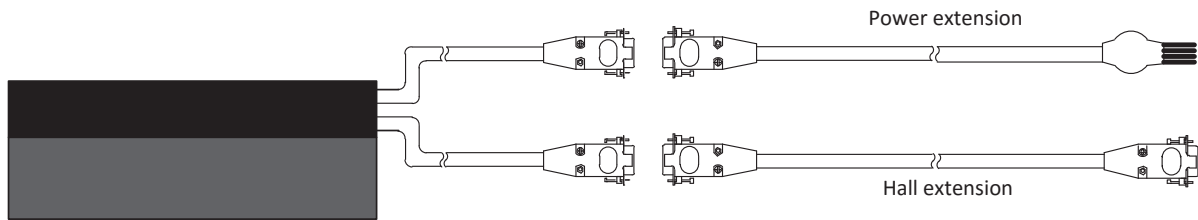
OPTICAL LIMIT SWITCH (PM-L24)



+5V dc	Brown
GND	Blue
LIGHT-ON	Black
DARK-ON	White

STAGE 2 PIAB EXTENSION CABLE

Connection example: PIAB-P1-S-TM-1.0-FC-HC-E1.0-O-1060-00



Extension Cable		Part Number																				
Power Extension Cable		CBL_EXT_PWR_PIXA_X.X																				
		CBL_EXT_PWR_PIXA_CC_X.X																				
Hall Sensor Extension Cable		CBL_EXT_HALL_PIXA_X.X																				
		CBL_EXT_HALL_PIXA_CC_X.X																				
Encoder Extension Cable	<table border="1"> <thead> <tr> <th colspan="2">CABLE</th> <th colspan="2">CABLE LENGTH (X.X)</th> </tr> </thead> <tbody> <tr> <td>01</td> <td>RH200 Digital</td> <td>0.5</td> <td>0.5 meter</td> </tr> <tr> <td rowspan="5">01B</td> <td rowspan="5">RH200 Analog</td> <td>1.0</td> <td>1.0 meter</td> </tr> <tr> <td>2.0</td> <td>2.0 meter</td> </tr> <tr> <td>3.0</td> <td>3.0 meter</td> </tr> <tr> <td>4.0</td> <td>4.0 meter</td> </tr> <tr> <td>5.0</td> <td>5.0 meter</td> </tr> </tbody> </table>	CABLE		CABLE LENGTH (X.X)		01	RH200 Digital	0.5	0.5 meter	01B	RH200 Analog	1.0	1.0 meter	2.0	2.0 meter	3.0	3.0 meter	4.0	4.0 meter	5.0	5.0 meter	CBL_EXT_REN01_X.X
		CABLE		CABLE LENGTH (X.X)																		
		01	RH200 Digital	0.5	0.5 meter																	
		01B	RH200 Analog	1.0	1.0 meter																	
				2.0	2.0 meter																	
				3.0	3.0 meter																	
				4.0	4.0 meter																	
5.0	5.0 meter																					
	CBL_EXT_REN01B_X.X																					

Notes: 1. X.X is the length of the cable in meters 2. For customized cable length, contact PBA